Experimental study of thermal deformation in a 3D-printing process with polymer filament
T. Kobayashi, J. Nishii, M. Ishida, H. Furumoto, Y. Utsumi, H. Kanematsu, Cosmin Gruescu

To cite this version:

HAL Id: hal-03366798
https://hal.univ-lille.fr/hal-03366798
Submitted on 5 Oct 2021

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L’archive ouverte pluridisciplinaire HAL, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d’enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

Distributed under a Creative Commons Attribution - NonCommercial - NoDerivatives| 4.0 International License
EXPERIMENTAL STUDY OF THERMAL DEFORMATION IN A 3D-PRINTING PROCESS WITH POLYMER FILAMENT

T. Kobayashi1, J. Nishii1, M. Ishida1, H. Furumoto2, Y. Utsumi3, H. Kanematsu4 and C. Gruescu5

1Department of Electronics & Control Engineering, National Institute of Technology, Tsuyama College, 624-1 Numa, Tsuyama, Okayama 708-8509, Japan.

2Department of Industrial Engineering, Hiroshima Kokusai Gakuin University, 6-20-1 Nakano, Aki-Ku, Hiroshima 739-0321, Japan.

3Laboratory of Advanced Science and Technology for Industry, University of Hyogo, 3-2-1 Kouto, Kamigori-Choo, Ako-Gun, Hyogo 678-1297, Japan.

4Department of Materials Science & Engineering, National Institute of Technology, Suzuka College, Shiroko-cho, Suzuka, Mie 510-0294, Japan.

5Department GMP, Institute Universitaire de Technologie A de Lille, BP 90179, 59653 Villeneuve d’Ascq Cedex, France.

Corresponding Author’s Email: 1t-koba@tsuyama-ct.ac.jp

Article History: Received 7 December 2018; Revised 22 February 2019; Accepted 17 April 2019

ABSTRACT: Thermal deformation generated in a 3D-printing process was investigated mainly by the measurement of the radius of curvature. 3D-printing have been widely applied in industrial products. High end models of 3D-printer have heating and heat retention function to reduce thermal deformation and further they have sometimes equipped with a computational simulation code to predict the thermal deformation. In the present study, a predicting method of thermal deformation for a low end 3D-printer was investigated so that the investment for the equipment is minimized, then the following results were obtained. Dominating parameters were quantified by the measurement and multiple regression analysis of proto-typed products with different dimensions, that is, it was found that the parameters having greater influence on the deformation were in the order of the amount of filament, the length, the width, the height, bottom area, the volume and the manufacturing time, respectively. A simple but convenient regression equation was obtained which will be used for an estimation and simulation of the thermal deformation in production with the 3D-printer without using any expensive simulation code.

KEYWORDS: Thermal Deformation; 3D Printer; Polymer Filament; Predicting Method; Multiple Regression Analysis
1.0  INTRODUCTION

In recent years, the presence of 3D printers is becoming indispensable as a means of development and invention [1-4]. The application fields have been widely expanded from construction, dentistry, medicine, electronics, automotive, robot and aerospace [5-11]. However, at the same time, several problems have already been filed. As a principle of 3D printer, it is a molding method (hot melt lamination method) in which a filler is melted then laminated and solidified, therefore "thermal deformation" generated in the process is one of the problems [12-13]. High end models of 3D-printer have heating and heat retention function with an enclosure to reduce thermal deformation, further they have sometimes equipped with a computational simulation code to predict the thermal deformation [14-16]. However, low end models are desirable as long as the deformation can be acceptable or predictable, from a view of economical. In the present study, a predicting method of thermal deformation for a low end 3D-printer using regression analysis was investigated without using expensive simulation code, so that the investment for the equipment is minimized.

2.0  METHODOLOGY

The members prototyped with a 3D printer are a 1/10 reduced model of the lower body of the actual mobile suit, which has a height of 7 m as shown in Figure 1. As large the members, a total of nine members, feet, legs, and thighs were fabricated as shown in Figure 2 and as small members, joint members and cylinders were trial manufactured shown in Figure 3.

![Figure 1: A 1/10 reduced model of the lower body of the actual mobile suit having a height of 7 m](image)
2.2 Equipment and Condition

The 3D printer used is "Makerbot Replicator +" (produced by Makerbot Co, Ltd). This 3D printer is a type of printer without the enclosure described above. The nozzle for filament moves only in the horizontal direction, and the base floor is raised and lowered in vertical direction. The filament used is "MakerBot 1.75 mm PLA large spool (gray, white)". It should be noted that the PLA filament is an environmentally decomposable resin [17]. The 3D CAD data were converted to the STL file formats and supplied to the printer. It is possible for the printer to add a function called "support". This function makes possible to form overhung portion without collapse by constructing vertical posts, further at the same time, the strength of
the hollow parts are also improved [17]. Therefore, the effect of with and without support on deformation were also investigated. After the proto-typed, the thermal deformation was measured as the radius of curvature in the direction of the length as shown in Figure 4.

![Figure 4: Measurement of the radius of curvature (thermal deformation)](image)

2.2 Equipment and Condition

The 3D printer used is "Makerbot Replicator +" (produced by Makerbot Co, Ltd). This 3D printer is a type of printer without the enclosure described above. The nozzle for filament moves only in the horizontal direction, and the base floor is raised and lowered in vertical direction. The filament used is "MakerBot 1.75 mm PLA large spool (gray, white)". It should be noted that the PLA filament is an environmentally decomposable resin [17]. The 3D CAD data were converted to the STL file formats and supplied to the printer. It is possible for the printer to add a function called "support". This function makes possible to form overhung portion without collapse by constructing vertical posts, further at the same time, the strength of the hollow parts are also improved [17]. Therefore, the effect of with and without support on deformation were also investigated. After the proto-typed, the thermal deformation was measured as the radius of curvature in the direction of the length as shown in Figure 4.

![Figure 4: Measurement of the radius of curvature (thermal deformation)](image)

2.3 Temperature Distribution and Temperature Change

In order to examine the degree of thermal deformation, a rectangular box of 20 mm in length and 10 mm in height as shown in Figure 5 was prepared as a specimen. Then, the temperature distribution was measured using the radiation type thermometer after its preparation stage and fabrication. In the preparation stage, the ceiling of the sample was measured every minute, and the whole image was measured after preparation. The filament (resin) melts out, and the temperature of the nozzle at the start of fabrication was 215°C. As shown in Figure 6, the temperature of the molded part was around 100°C at the beginning of the production, however after the lamination is superposed, the temperature of the molded part rose to about 120°C. This is considered to be due to the fact that the heat of the already laminated part is accumulated when newly laminating, and it is not completely cooled. In addition, the sample shown in Figure 5 was completed in about 8 minutes. The temperature from the bottom steadily declined and converged to about room temperature. The temperature measured after completion (9 to 10 minutes) is shown in Figure 7. In the temperature distribution shown in Figure 7, the minimum temperature was set at 24°C (Room temperature) and the maximum temperature was set at 55°C (Ceiling). The temperature is already lower than the ceiling (red and white), but the part at the beginning (yellowish green) is lowered to room temperature from 24 to 30°C, as shown in Figure 7, the top is not completely cooled even after completion.
3.1 Multiple Regression Analysis

When analyzing, the necessary condition is called "independent variable" for example, if a rent for an apartment (one room) is estimated, the independent variable will be the distance from the
station, the size of the room, the age of years, the popularity and the influence factor from the independent variables will be found to the conclusion. For the analysis to be performed this time, independent variables are the vertical dimension, the horizontal dimension, the height, the bottom area, the volume, with or without of support, the production time and the amount of filament used.

Multiple regression analysis was performed on the independent variables and the measurement results of the radius of curvature of each member. Figure 8 shows the comparison between the measured values and the results calculated from the regression equation.

![Figure 8: Comparison of the radius of curvature between the measured and the results calculated from the regression equation](image)

![Figure 9: Comparison of the radius of curvature between the measured and the results calculated from the regression equation (regarding relatively large members)](image)
Next, we divide it into the large and small members and multiple regression analysis was performed again. The results are then shown in Figures 9 and 10. The multiple correlation $R$ was showed 0.996, which proved a very good correlation for the small members (Figure 10). The multiple correlation $R$ decreased slightly from 0.805 to 0.749 for the large members (Figure 9). Therefore, it was found that the correlation varies depending on the size of the member.

![Graph showing comparison between measured and calculated radius of curvature for various members.](image)

**Figure 10**: Comparison of the radius of curvature between the measured and the results calculated from the regression equation (regarding relatively small members)

### 3.2 Influence Factor

Influence factor of each parameter which is the object of this research was obtained by the following equations and the results are summarized in Figure 11.

$$ IF = RC \times Ra \quad (1) $$

$$ Ra = maxX_i - minX_i \quad (2) $$

where IF is the influence factor, $RC$ is the regression coefficient, $Ra$ is the range of each parameter, $maxX_i$ is the maximum value of each parameter and $minX_i$ is minimum value of each parameter. From Figure 11, it was found that the parameters having greater influence on deformation were in the order of the amount of filament, the length, the width, the height, bottom area, the volume, the manufacturing time and the length, respectively.
Figure 11: Influence factor of each parameter on the radius of curvature

4.0 CONCLUSION

In the present study, a predicting method of thermal deformation for a low end 3D-printer was investigated. Dominating parameters were quantified by the measurement and multiple regression analysis of proto-typed products with different dimensions, that is, it was found that the parameters having greater influence on deformation were in the order of the amount of filament, the length, the width, the height, bottom area, the volume and the manufacturing time, respectively. A simple but convenient regression equation was obtained for an estimation and simulation of the thermal deformation in production with the 3D-printer without using any expensive simulation code.

REFERENCES


