



# multiTOUCH

## Technological issues with multimodal touch input devices

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- 1 Introduction
- 2 Multimodality
- 3 Available Technologies
- 4 Some examples
- 5 Summary and Conclusion

- What is a Multimodal Touch Input Device?

It's the combination of haptic feedback with one or more modalities



Visual

Haptic

Auditory

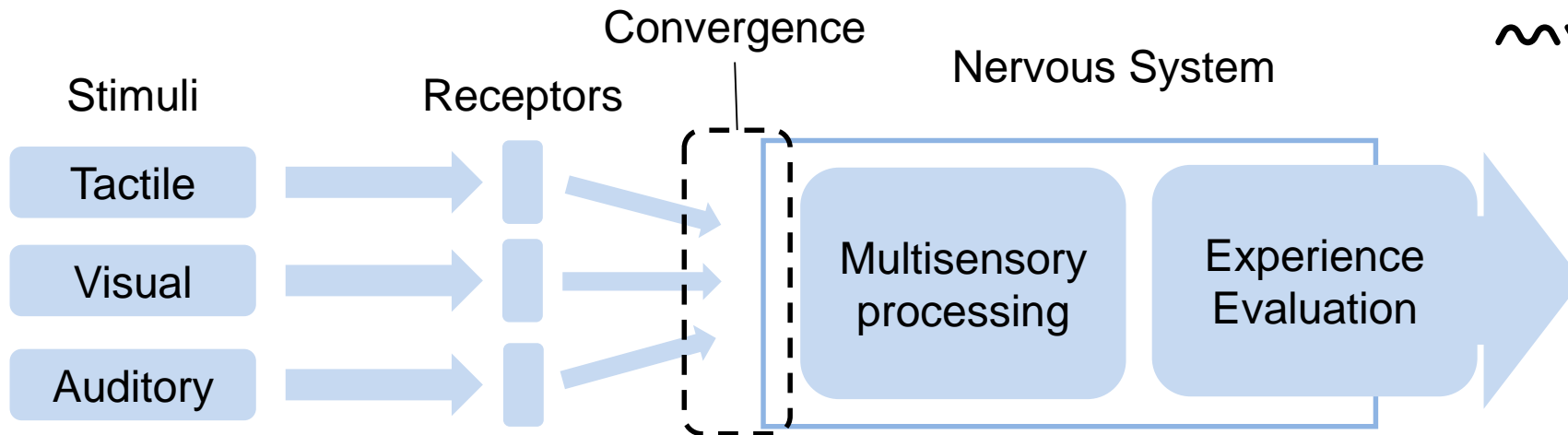
Screens  
AR glasses  
VRHMD  
Peripheral light

Speakers  
Headphones





### □ How Multimodality works



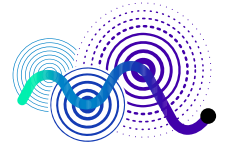
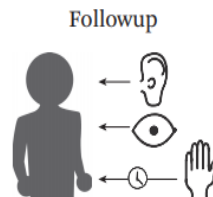
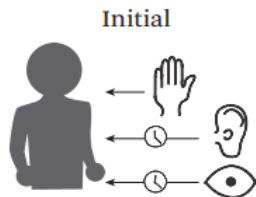
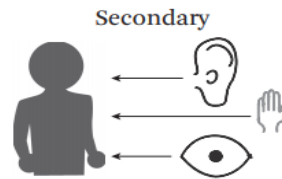
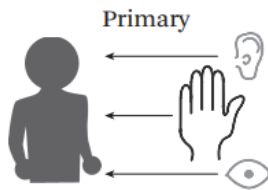
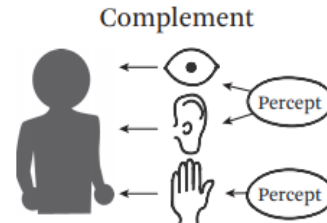
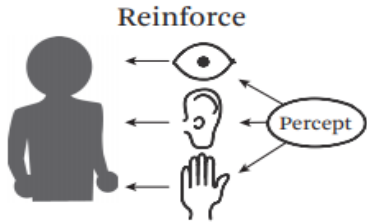
Convergence → Moments when information from different modalities meets

Multisensory processing → Integration of the received information

Experience Evaluation → Different layers

# Multimodality

## ❑ Multisensory Haptic Interactions: Information relationship



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Information Relevance

Temporal-Detail

# Multimodal interfaces

## ❑ Fusion-based

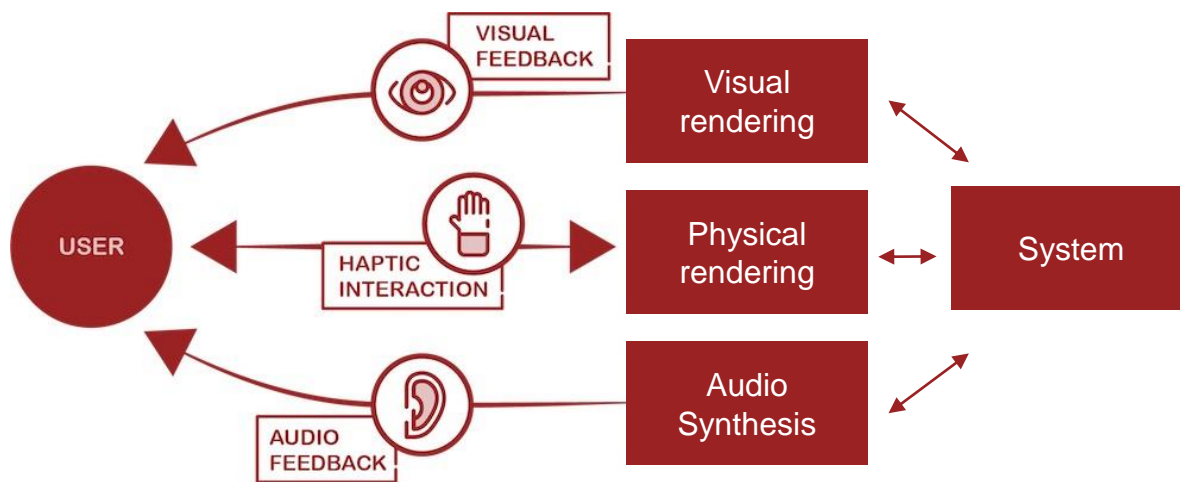
- Co-process input modes
- Optimized to support a specific range of tasks

## ❑ Temporally cascaded

- Modes integrated depend on temporal aspects
- Under-exploited considering others.



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## Approaches

Single model

Distributed

# Available Technologies

## □ Haptic classification

### 3 S of haptics

Shape

Global, Local

Substance

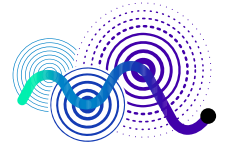
Mass, Stiffness, etc.

Surface

Texture, Friction, Temperature

### Touch input device Classification

Tactile feedback devices



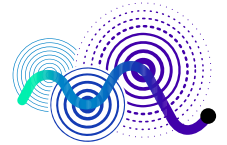
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# Available Technologies



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## Tactile feedback devices

### Mechanical Vibration

### Surface shape changing

### Friction Modulation

ERM

LRA

Piezoelectric

Voice coil

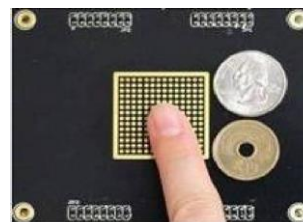
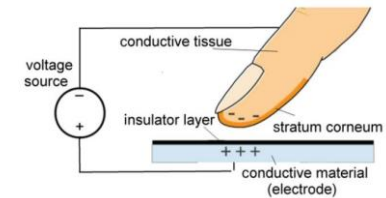
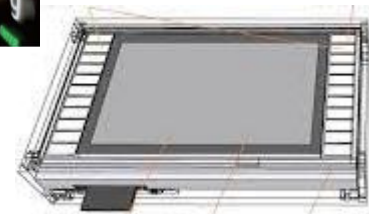
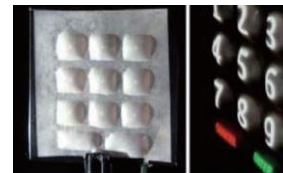
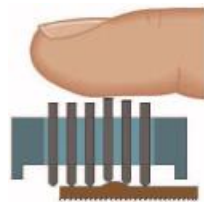
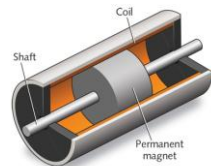
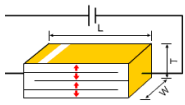
Pin Array

Electrode array

Pneumatic chamber

Ultrasonic vibration

Electrostatic effect



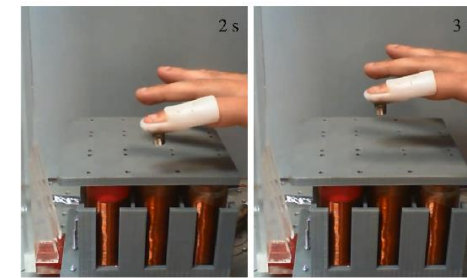
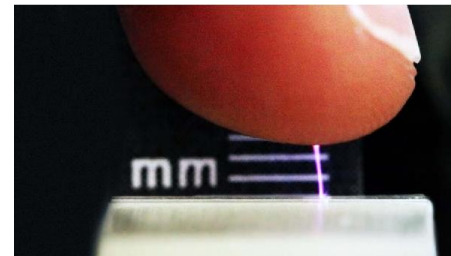
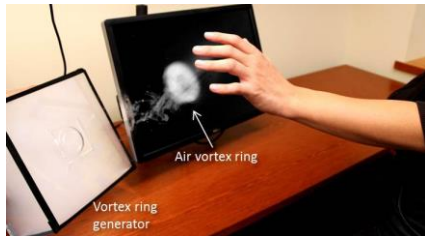
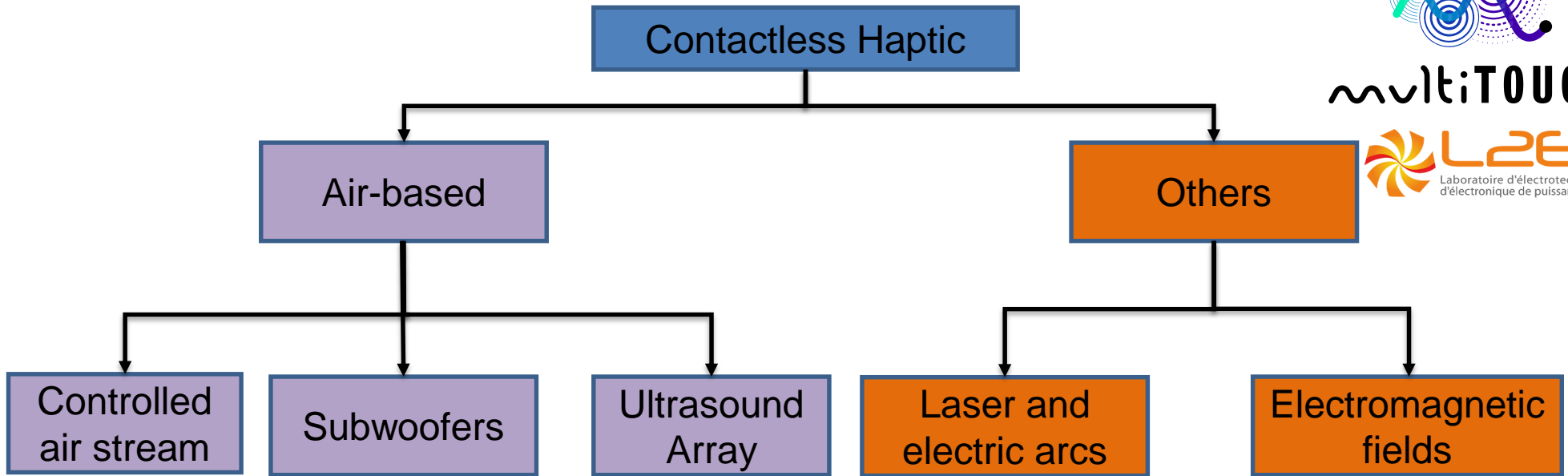
1-Wang, D., Y. Guo, S. Liu, Yuru Zhang, Weiliang Xu and Jing Xiao. "Haptic display for virtual reality: progress and challenges." Virtual Real. Intell. Hardw. 1 (2019): 136-162.

2- Basdogan, C., F. Giraud, Vincent Lévesque and S. Choi. "A Review of Surface Haptics: Enabling Tactile Effects on Touch Surfaces." IEEE Transactions on Haptics 13 (2020): 450-470.



# Available Technologies

## □ Another category, Contactless Haptic Technologies



1-S. Gupta, D. Morris, S. Patel, and D. Tan, "AirWave: Non-Contact Haptic Feedback Using Air Vortex Rings," in Proceedings of UbiComp '13, 2013, pp. 419–428.  
 2-S. Hashizume, A. Koike, T. Hoshi, and Y. Ochiai, "Sonovortex: Rendering multi-resolution aerial haptics by aerodynamic vortex and focused ultrasound," Proc. SIGGRAPH '17 Posters, 2017.  
 3-D. Spelmezan, D. R. Sahoo, and S. Subramanian, "Sparkle: Hover Feedback with Touchable Electric Arcs," in Proceedings of the SIGCHI Conference on Human Factors in Computing Systems - CHI '17, 2017, pp.  
 4-A. Adel, M. Micheal, M. Self, S. Abdennadher, and I. Khalil, "Rendering of Virtual Volumetric Shapes Using an Electromagnetic-Based Haptic Interface," Proc. IEEE/RSJ Int. Conf. Intell. Robot. Syst. - IROS '18, 2018.

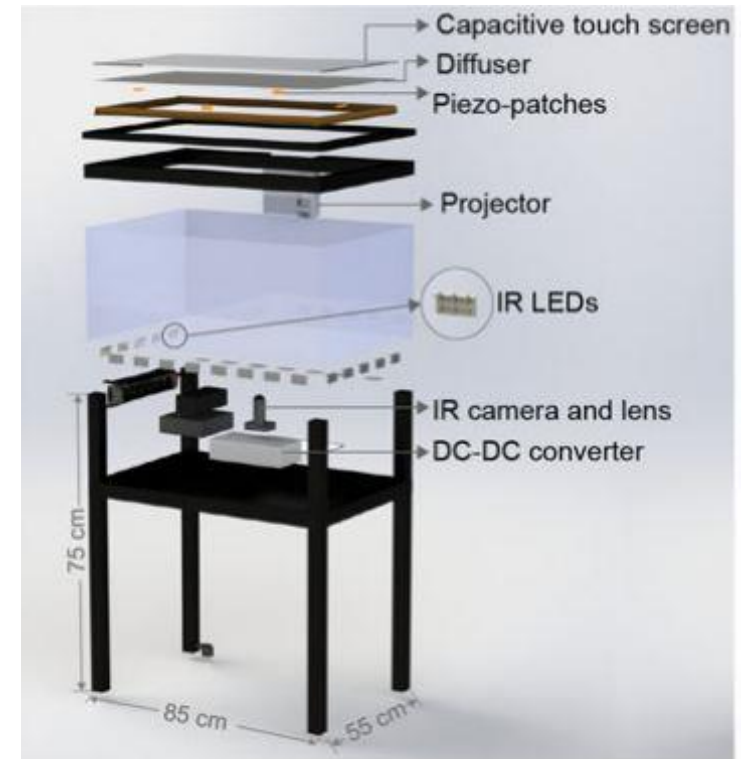
## Examples #1

### □ HapTable: A multimodal visual-haptic system



#### 3 main modules:

- Gesture detection
- Visual display
- Haptic feedback
  - Electromechanical piezo - static gesture
  - Electrostatic actuation - dynamic gesture



Experiment 1: Vibrotactile Flow

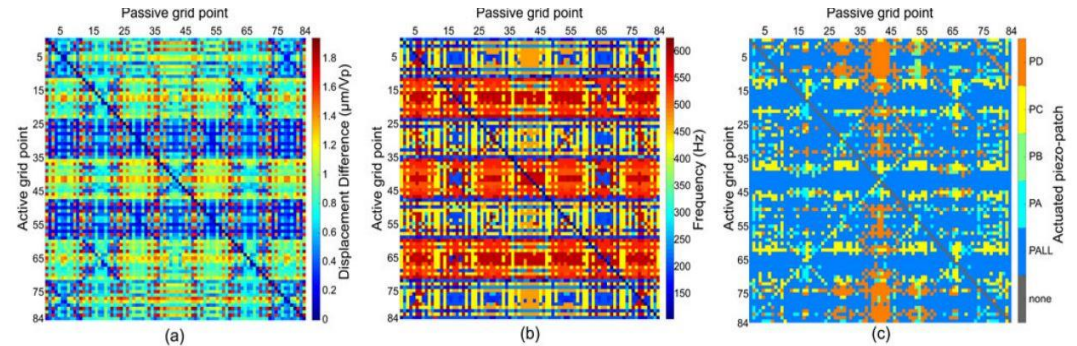
Experiment 2: Haptic knob

# Example #1

## □ HapTable: A multimodal visual-haptic system

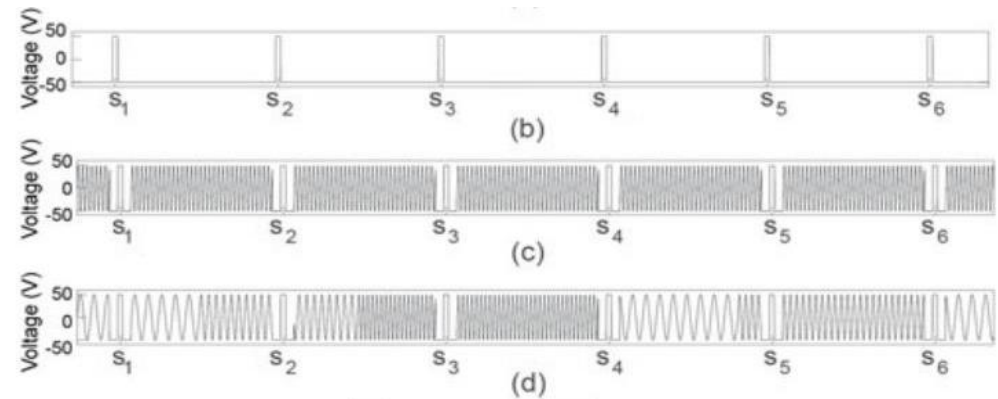
### ■ Piezoelectric actuators

- Vibration maps
  - Displacement difference
  - Frequency
  - Actuated Piezo patch



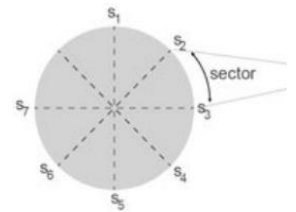
### ■ Electrostatic Force

- Different sectors is mapped to an item on the menu
  - (b) haptic detent at sector crossings
  - (c) haptic detent and constant friction
  - (d) haptic detent and velocity-based friction



### ■ Results

Adding haptic\_feedback to a virtual knob improves interaction quality, user experience, and also the confidence of the user



## Examples #2

### ❑ Multimodal In-Vehicle Interactive System

#### ▪ **Haptic**

ERM used to provide additional information. Different vibration stimuli were generated based on user position or gestures.

#### ▪ **Auditory**

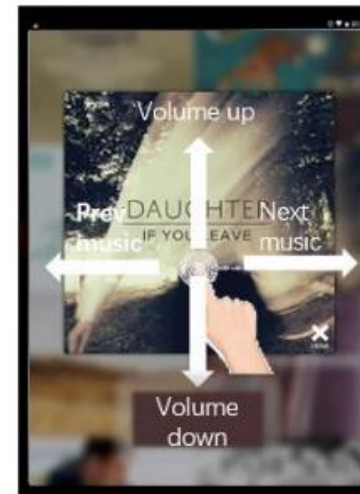
Used to confirm completion of a gesture or to give additional information such as the chosen button.

#### ▪ **Visual**

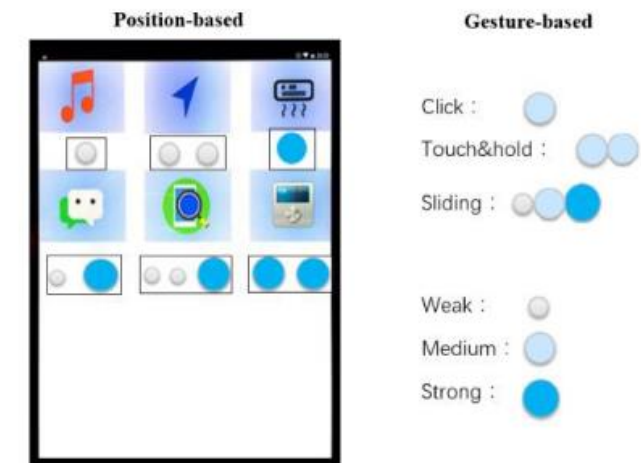
Classical Tablet

#### ➤ 5 trials:

1. Only Vision – no driving
2. Visual and Auditory
3. Visual and haptic
4. Visual and Auditory and Haptic
5. Multimodal – no driving



Sliding gesture interaction



Vibration schematic diagram

## Examples #2

- ❑ Multimodal In-Vehicle Interactive System's
  - Driving simulation while completing a secondary task on the tablet.  
Instructions given as text and speech  
Eye tracker and gaze calibration



No significant difference  
between trials in terms of

- ❖ The Accuracy and Completion Time
- ❖ Lane Deviation

Significant difference

- ❖ Glance Time Off Road → T 4 (M=0.397s, SD=0.021)  
T 1 (M=0.934s, SD=0.102)
- ❖ Perception Questionnaire → Multimodal rated more  
than other conditions

Completing a secondary task with the multimodal touchscreen could  
not have an influence on driving Efficiency or safety but improves  
the user experience



## Examples #3

### ❑ Augmenting In-vehicle Voice and Tactile interface

#### Usability Issues

- Speak or wait
- Short term memory dependency
- Error recognition and error correction difficulties are other usability issues of the VUI

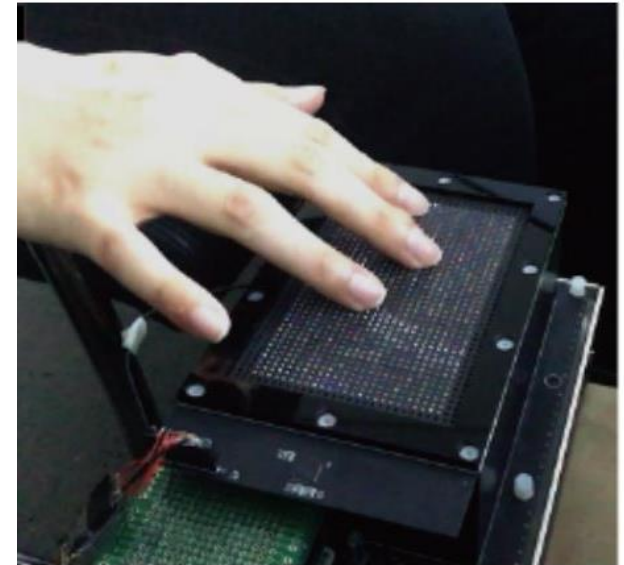


Speech recognition module  
Google Cloud Speech API

Pin-array haptic feedback  
40 × 25 pin grid with 2.5 mm spacing

Primary task: Change lane when a sign is displayed

Secondary task: train reservation or Message sending



## Examples #3

### ❑ Augmenting In-vehicle Voice and Tactile interface

Secondary task train reservation(TR) or Message sending(MS)



#### • Task Completion Time

Voice+Tactile was significantly shorter than Voice-only for both TR and MS

#### • Driving performance

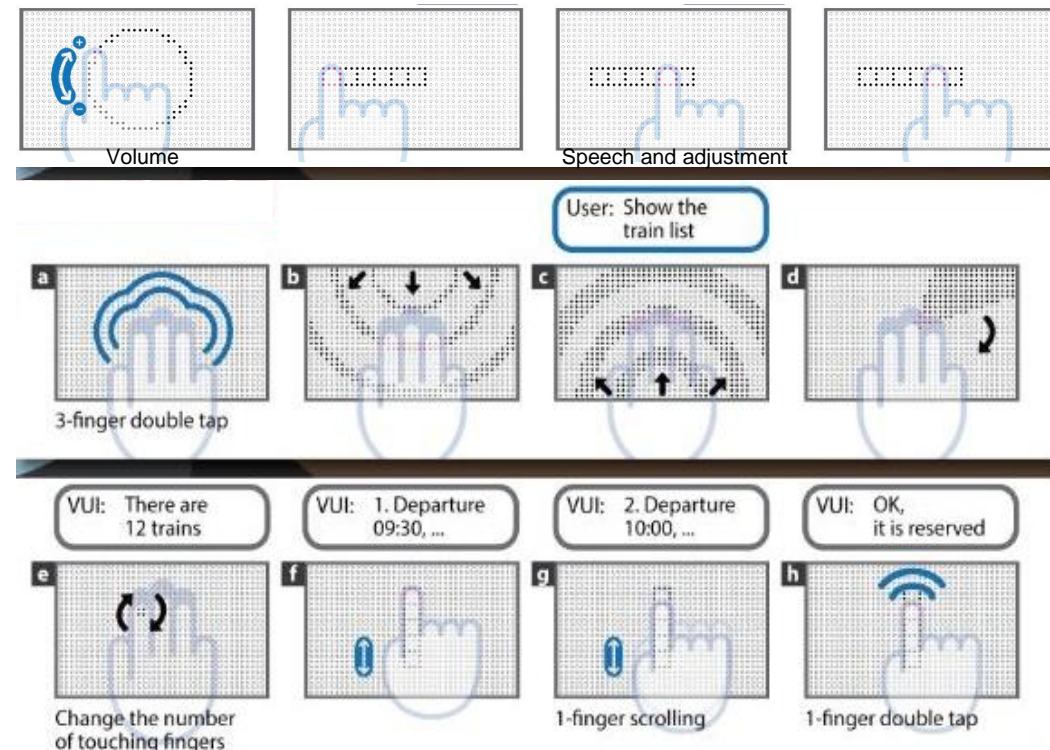
Neither interfaces had a significant effect on driving performance for both TR and MS

#### • Gaze Behavior

They only looked at the device to locate it and place their right hand on it ( $t < 1s$ )

#### • Task Workload

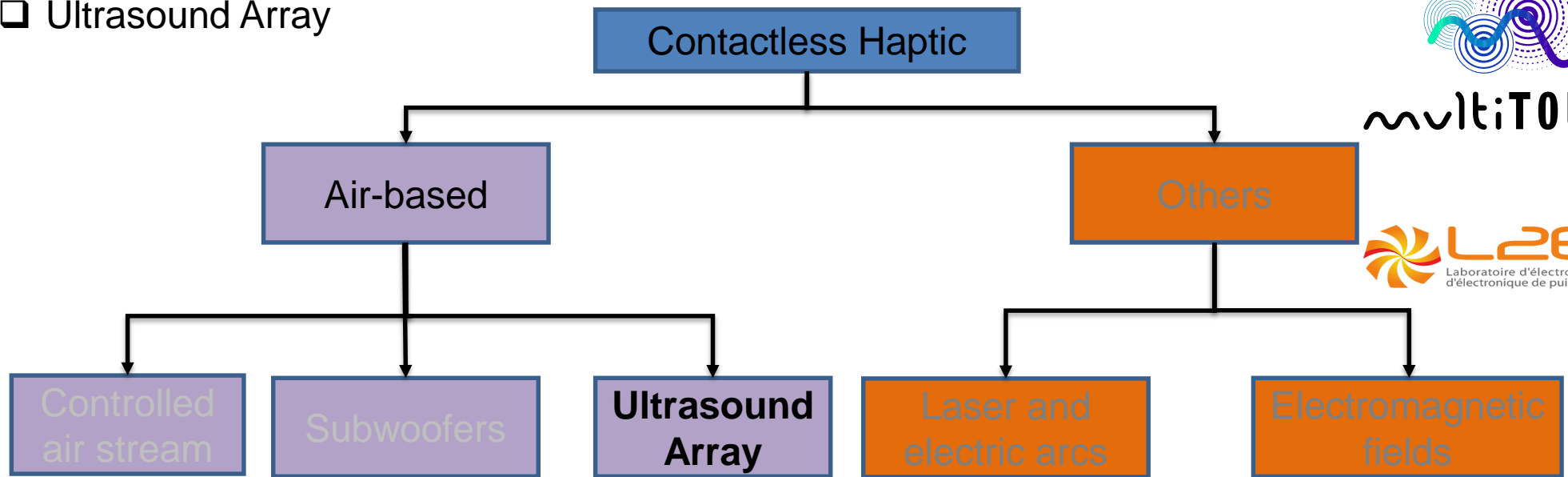
Higher for TR vs MS but no significant difference between Voice+Tactile and Voice-only



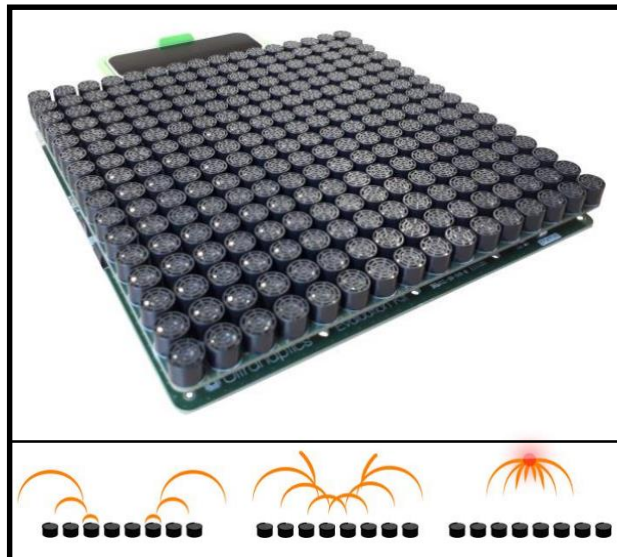


# Available Technologies

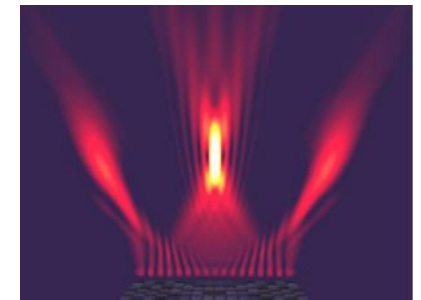
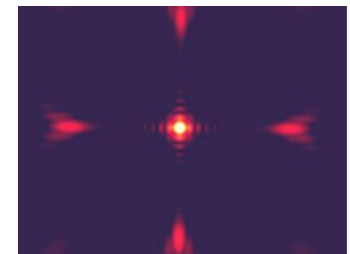
## ❑ Ultrasound Array



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- Precision
- Strength and Perception
- Range
- Size, Weight, Cost, Power consumption, Heat dissipation
- Noise

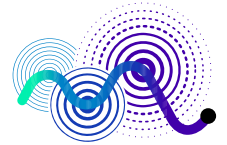
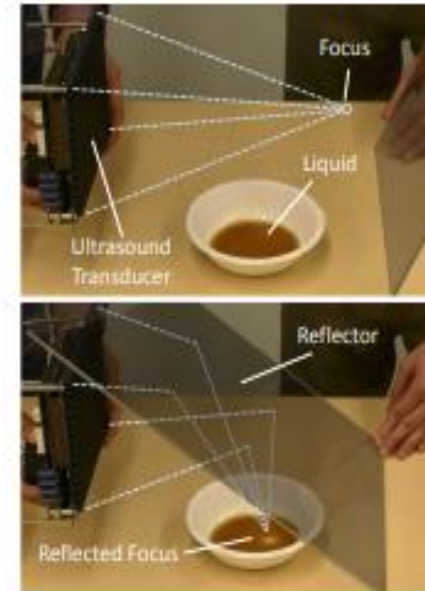


## Example #1

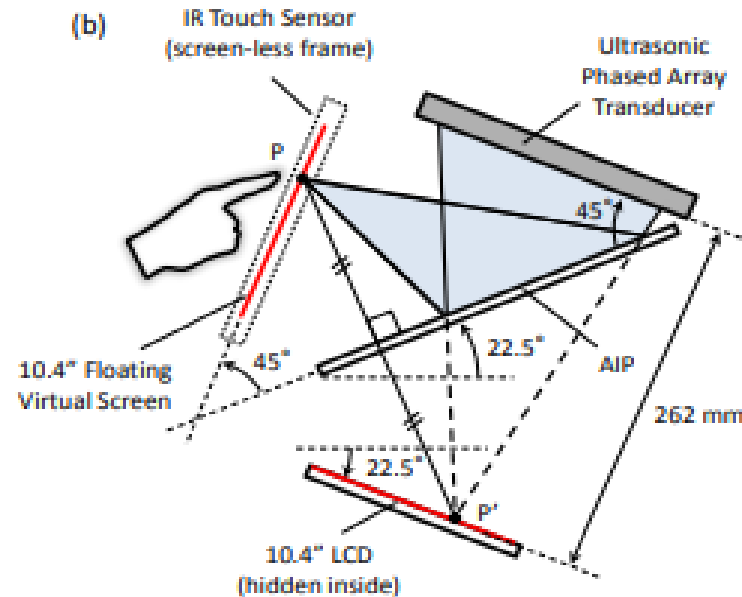
### □ Haptomime

#### ▪ Main components

- A liquid crystal display (LCD)
- An Aerial Imaging Plate (AIP)
- Embedded speakers
- An ultrasonic phased array transducer



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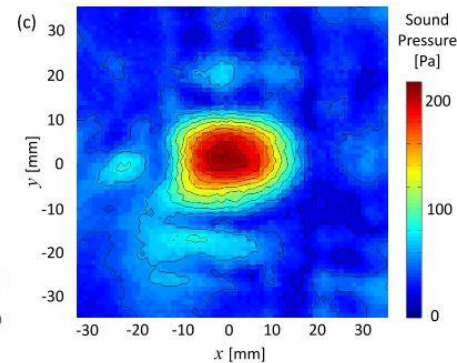
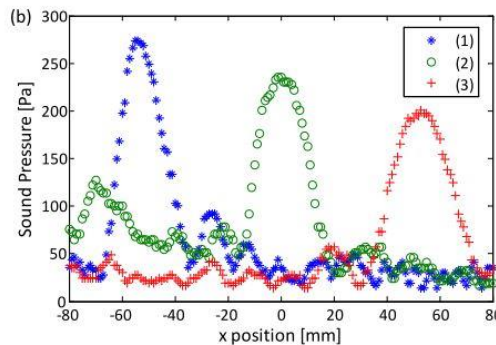
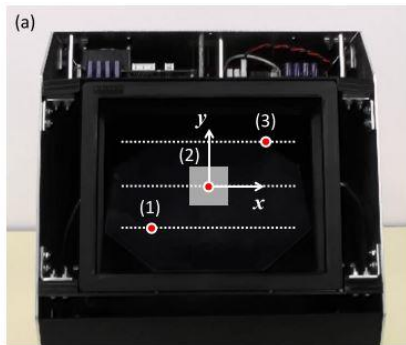
# Example #1

## □ Haptomime

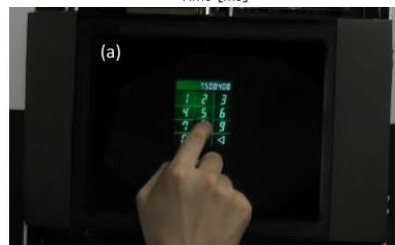
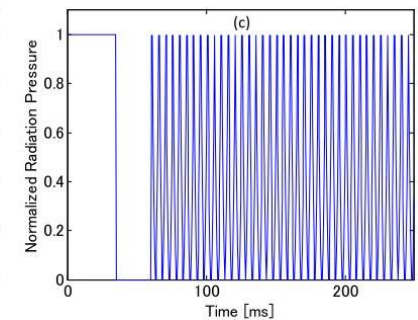
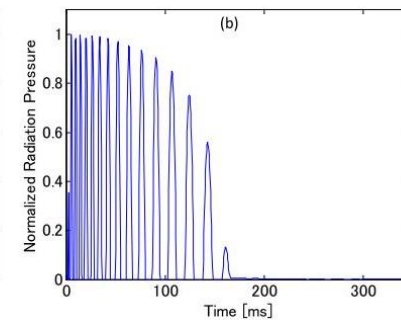
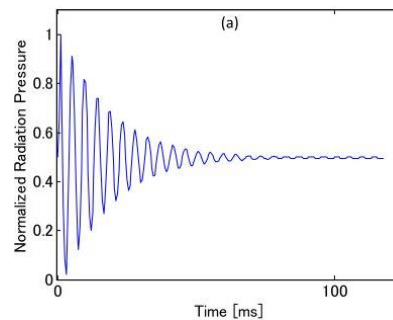
The entire system is controlled by a Windows 7 computer that drives the LCD and the ultrasonic transducer based on the data acquired from the IR touch sensor.



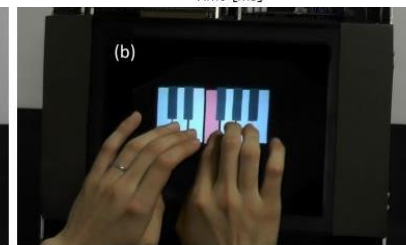
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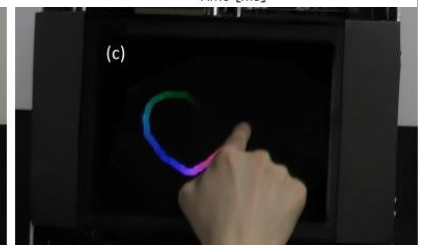
- Haptic represent a crucial feedback for the system
- AIP has a narrow angle view
- Signal modulation reduce the perceived stimuli



keypad



Piano



Drawing

## Example #2

### □ Mid-Air Gesture Interaction in Cars

#### ▪ **Haptic**

Mid-air Ultrasound haptic

- 500 ms functional feedback on the palm
- Circular gesture - circular motion
- 500 ms at index - Victory gesture
- Swipe – wall moving accordingly

#### ▪ **Auditory**

Headphones

- Note associated with gesture with a duration of 300ms

#### ▪ **Visual**

Monitor

LED strip

- Swipe – Yellow light mimicking the gesture direction
- Circular – Blue light incrementing (CW/CAW)
- V – Blue light from ends to centre strip or RED



Figure 2. Experiment set-up.

5 conditions:

V

U

AU

AU

UP

## Example #2

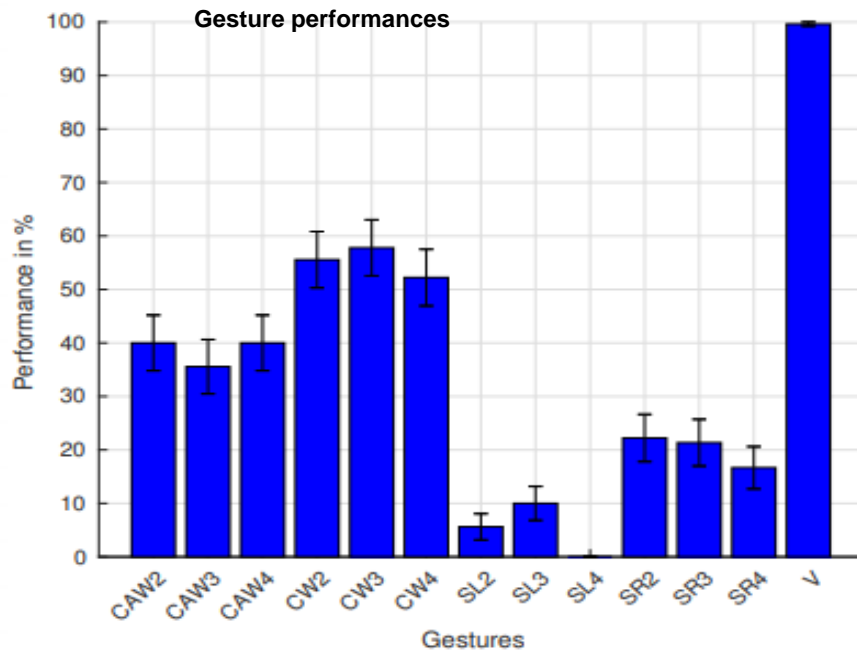
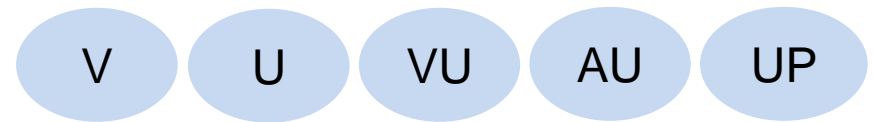
### □ Mid-Air Gesture Interaction in Cars

Change lane while performing a second task (gesture):

- pop up message box - bottom of the screen
- speech instructions - headphones



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| V       | U      | UV      | UA      | UP     |
|---------|--------|---------|---------|--------|
| 51.68%  | 21.11% | 46.29%  | 52.22%  | 47.40% |
| 10.06 s | 8.22 s | 10.16 s | 10.58 s | 9.98 s |

**Table 2. Secondary task performance (%) and duration (seconds) depending on condition. (V: visual; U: ultrasound; UV: ultrasound-visual; UA: ultrasound-audio; UP: ultrasound-peripheral.)**



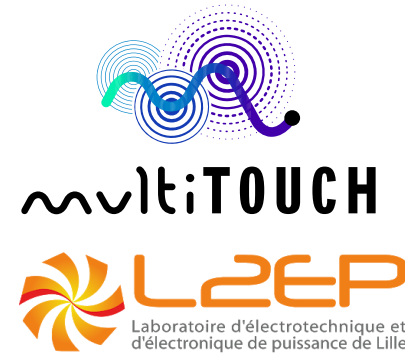
## Summary

### ➤ Technological limitations

- Simple actuators = simple control but less enhancing
- Complex actuation methods = more tactile feedback  
How to control the system for more realistic feedback
- Contactless technologies gives new possibilities but we still need to overcome limitations related with rendered and control of stimuli
- To find out the best multimodal input for an interface is still an open research question.

### ➤ Biological limitations

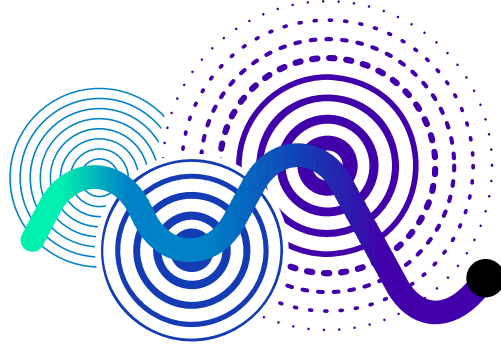
- Cognitive load while interacting with a MMIS
- Cognitive load with multiple modalities
- Integration of different modalities





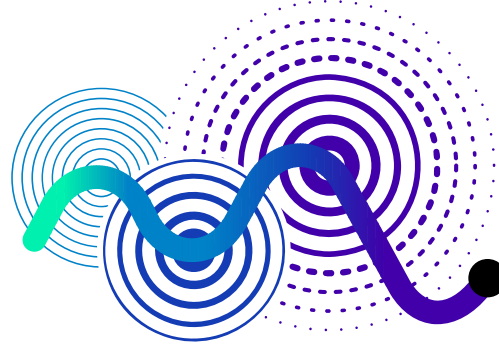
- Multimodality may increase task performance as the task gets gradually more difficult?
- Effectiveness of multimodality is scenario specific?
- Is our perception knowledge enough?
- Adding more cues could result in a masking effect of one over others?





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**THANKS FOR YOUR ATTENTION**



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**Questions?**